Errata for *A Mathematical Model and Calibration Procedure for Galvanometric Laser Scanning Systems*
Vision, Modeling, and Visualization (VMV 2011)
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These errata is with respect to the Proceedings of Vision, Modeling, and Visualization (VMV 2011), page 207-214.

p. 209 (p. 3 in the paper) Formula (3)

\[ x = r \cdot \tan \alpha \left( \frac{z_0 - r}{r \cdot \cos \beta} + 1 \right) \]
\[ y = (r - z_0) \cdot \tan \beta \]
\[ z = z_0 \]

p. 209 (p. 3 in the paper) Formula (6)

\[ t_x = \frac{\vec{n} \cdot \vec{O} - \vec{S}}{(\vec{n} \cdot \vec{l})} \]

p. 210 (p. 4 of the paper) Formula (9)

\[ t_y = \frac{\vec{k} \cdot \vec{Q} - \vec{P}}{(\vec{k} \cdot \vec{d})} \]

p. 210 (p. 4 of the paper) Formula (10)

\[ \vec{m} = -2 \cdot (\vec{k} \cdot \vec{d}) \cdot \vec{k} + \vec{d} \]

p. 212 (p. 6 of the paper) Formula (16)

\[ E(X^i) = \sum_{j=0}^{N} (\lambda \cdot (1 - (f^i \cdot h^i)) + d_j)^2 \cdot j = 1 \ldots M \]